

**Solution Methods:
Iterative Techniques
Lecture 6**

Motivation

Consider a standard second order finite difference discretization of

$$-\nabla^2 u = f,$$

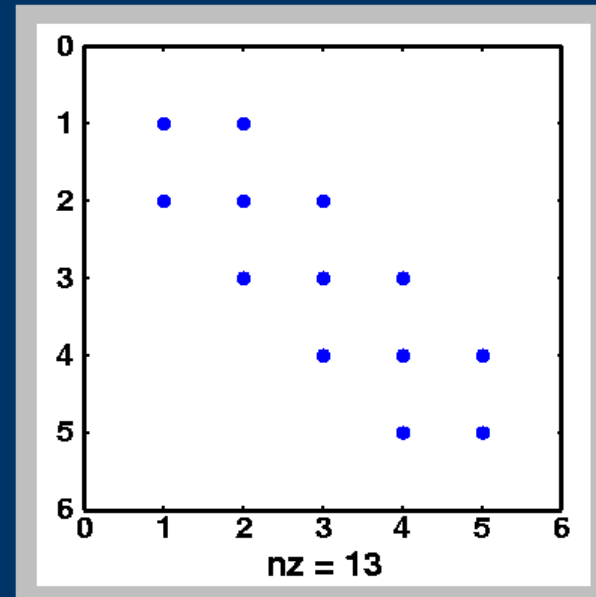
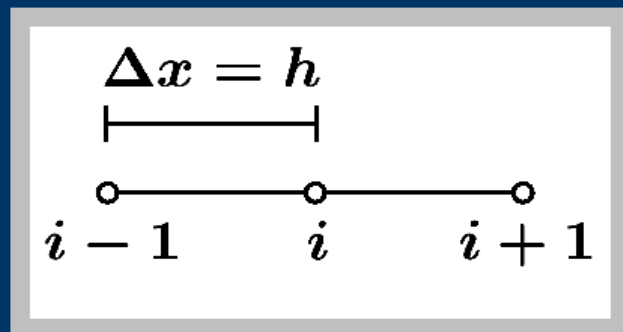
on a regular grid, in **1**, **2**, and **3** dimensions.

\Rightarrow

$$\mathbf{A} u = f$$

1D Finite Differences

Motivation



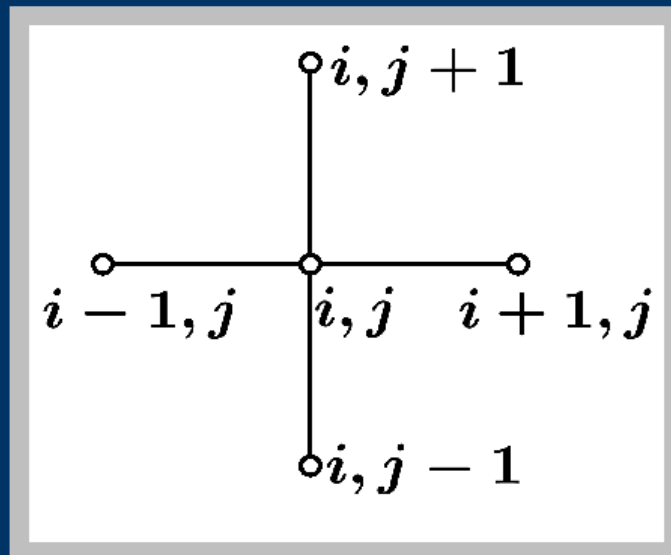
n points

$n \times n$ matrix
bandwidth $b = 1$

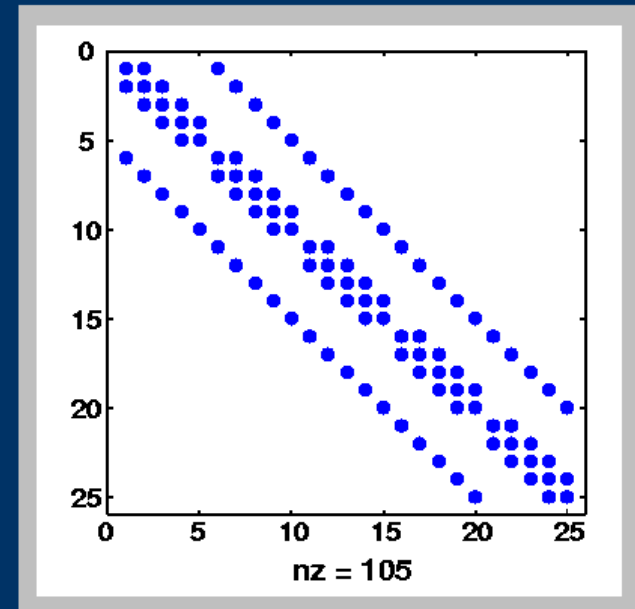
Cost of Gaussian elimination $O(b^2 n) = O(n)$

2D Finite Differences

Motivation



$n \times n$ points

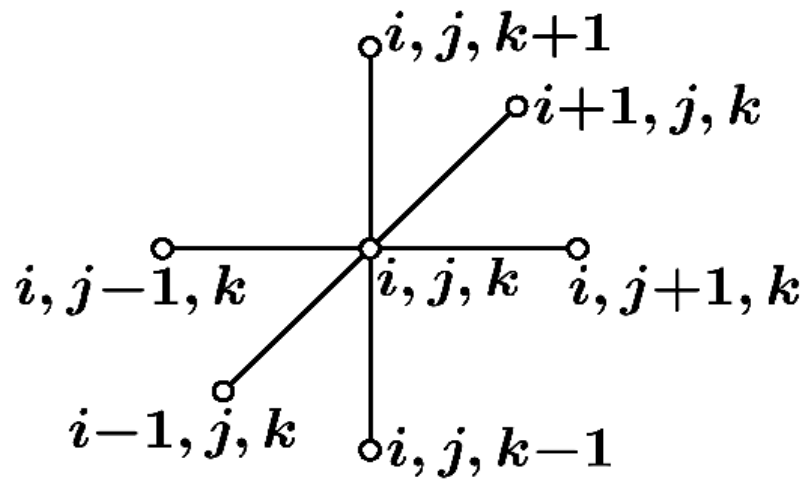


$n^2 \times n^2$ matrix
bandwidth $b = n$

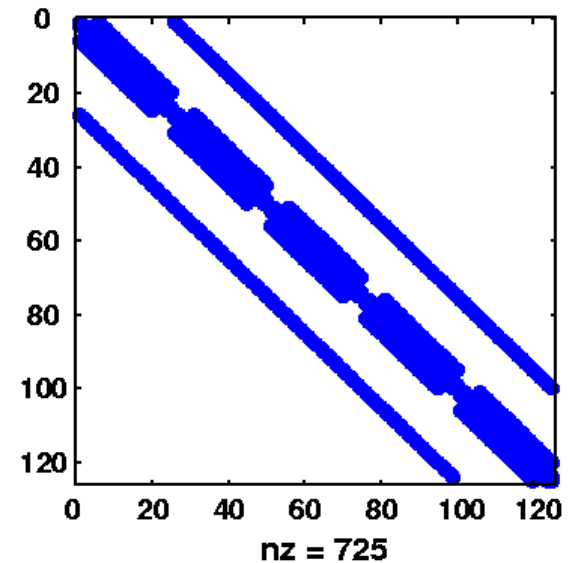
Cost of Gaussian elimination $O(b^2 n^2) = O(n^4)$

3D Finite Differences

Motivation



$n \times n \times n$ points



$n^3 \times n^3$ matrix
bandwidth $b = n^2$

Cost of Gaussian elimination $O(b^2 n^3) = O(n^7)$!

Basic Iterative Methods

Jacobi

Intuitive Interpretation...

Instead of solving

$$-u_{xx} = f,$$

we solve

$$\frac{\partial u}{\partial t} = u_{xx} + f,$$

N1

starting from an arbitrary $u(x, 0)$.

We expect $u(x, t \rightarrow \infty) \rightarrow u(x)$.

Basic Iterative Methods

Jacobi

...Intuitive Interpretation...

To solve

$$\frac{\partial u}{\partial t} = u_{xx} + f$$

we use an inexpensive (explicit) method.

For instance,
$$\frac{\hat{u}_i^{r+1} - \hat{u}_i^r}{\Delta t} = \frac{\hat{u}_{i+1}^r - 2\hat{u}_i^r + \hat{u}_{i-1}^r}{h^2} + \hat{f}_i$$

$$u = \{\hat{u}_i\}_{i=1}^n, \quad f = \{\hat{f}_i\}_{i=1}^n$$

$$u^{r+1} = u^r + \Delta t(f - Au^r) = (I - \Delta tA)u^r + \Delta t f.$$

Basic Iterative Methods

Jacobi

...Intuitive Interpretation

Stability dictates that

$$\Delta t \leq \frac{h^2}{2}$$

Thus, we take Δt as large as possible, i.e. ($\Delta t = h^2/2$).

$$\mathbf{u}^{r+1} = \left(\mathbf{I} - \frac{h^2}{2} \mathbf{A} \right) \hat{\mathbf{u}}^r + \frac{h^2}{2} \mathbf{f}$$

$$\Rightarrow \hat{u}_i^{r+1} = \frac{1}{2} (\hat{u}_{i+1}^r + \hat{u}_{i-1}^r + h^2 \hat{f}_i) \quad \text{for } i = 1, \dots, n.$$

Basic Iterative Methods

Jacobi

Matrix Form...

Split A

$$A = D - L - U \quad \left\{ \begin{array}{l} D: \text{Diagonal} \\ L: \text{Lower triangular} \\ U: \text{Upper triangular} \end{array} \right.$$

$$A u = f \text{ becomes } (D - L - U) u = f$$

Iterative method

$$D u^{r+1} = (L + U) u^r + f$$

Basic Iterative Methods

Jacobi

...Matrix Form

$$\begin{aligned}u^{r+1} &= D^{-1}(L + U) u^r + D^{-1} f \\&= D^{-1}(D - A) u^r + D^{-1} f \\&= (I - D^{-1}A) u^r + D^{-1} f\end{aligned}$$

$$u^{r+1} = R_J u^r + D^{-1} f$$

$R_J = (I - D^{-1}A)$: Jacobi Iteration Matrix

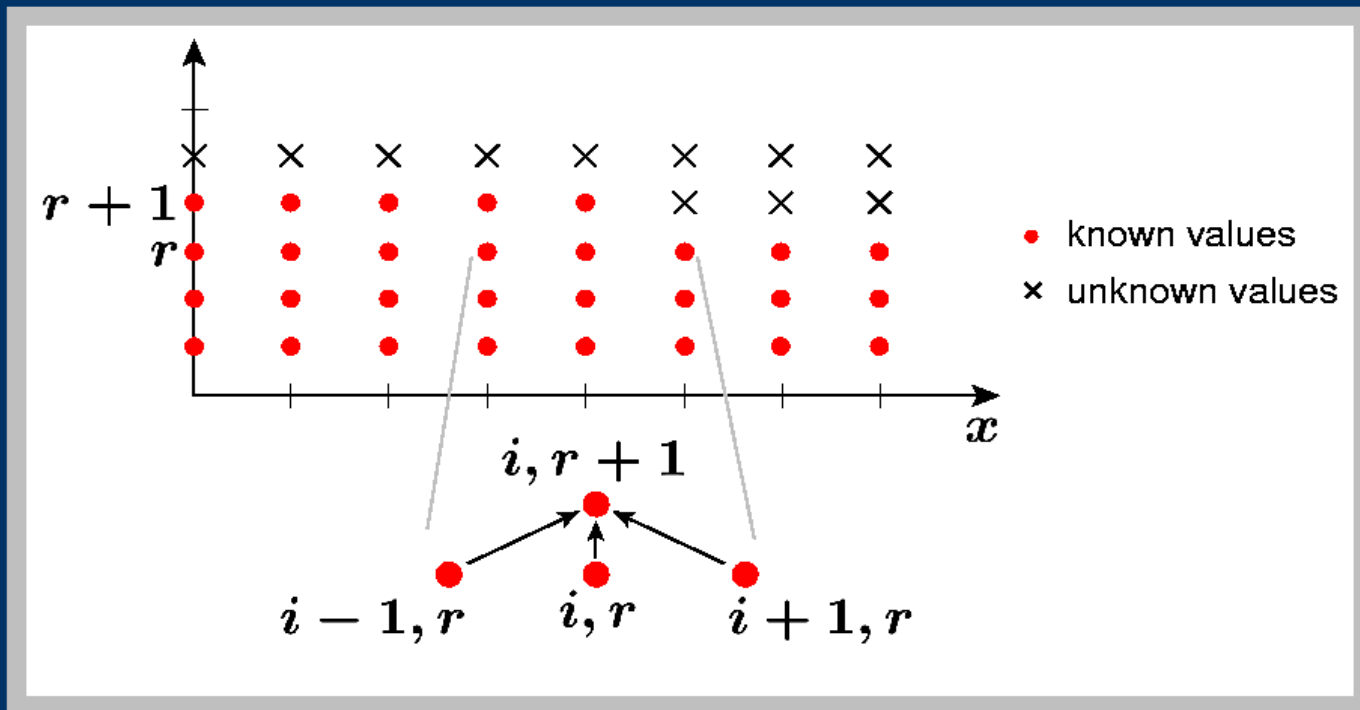
$$D_{ii}^{-1} = h^2/2$$

$$\Rightarrow \hat{u}_i^{r+1} = \frac{1}{2} (\hat{u}_{i+1}^r + \hat{u}_{i-1}^r + h^2 \hat{f}_i) \quad \text{for } i = 1, \dots, n$$

Basic Iterative Methods

Jacobi

Implementation

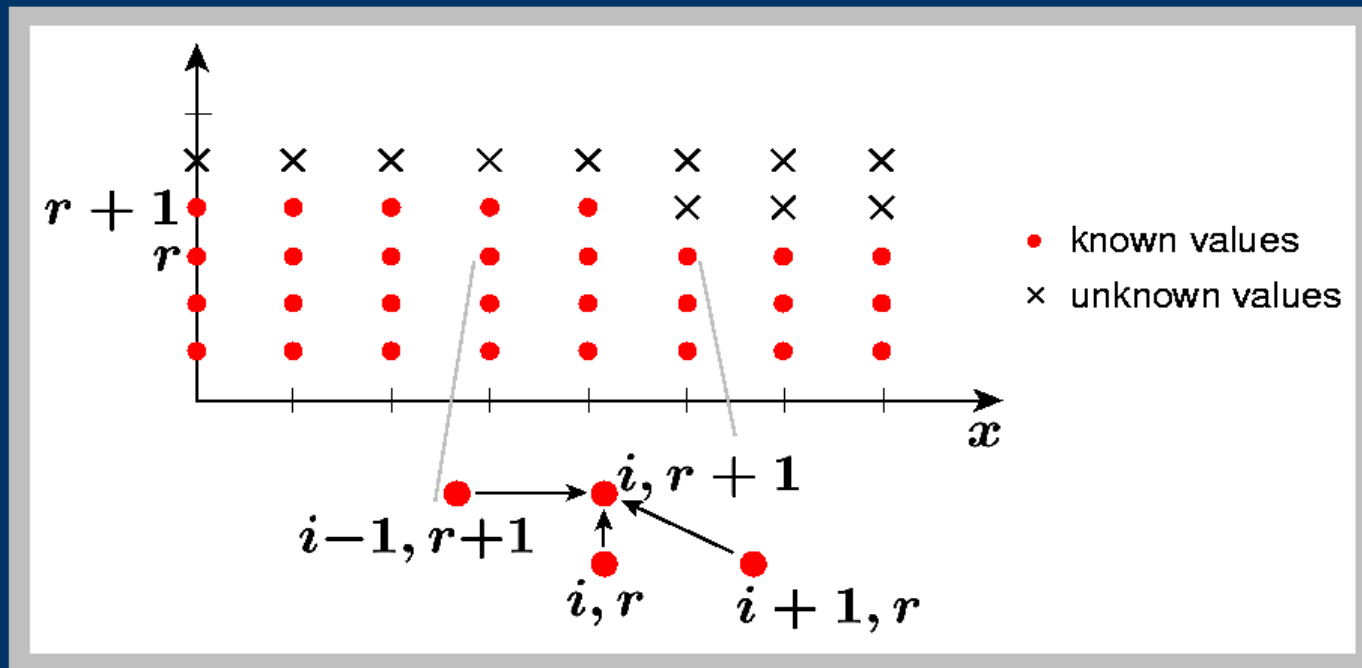


Jacobi iteration

$$u_i^{r+1} = \frac{1}{2} (u_{i+1}^r + u_{i-1}^r + h^2 f_i)$$

Basic Iterative Methods

Gauss-Seidel



Gauss-Seidel iteration (consider most recent iterate)

$$u_i^{r+1} = \frac{1}{2} (u_{i+1}^r + u_{i-1}^{r+1} + h^2 f_i)$$

Basic Iterative Methods

Gauss-Seidel

Matrix Form...

Split A

$$A = D - L - U$$

$$\left\{ \begin{array}{l} D: \text{ Diagonal} \\ L: \text{ Lower triangular} \\ U: \text{ Upper triangular} \end{array} \right.$$

$$A u = f \text{ becomes } (D - L - U) u = f$$

Iterative method

$$(D - L) u^{r+1} = U u^r + f$$

Basic Iterative Methods

Gauss-Seidel

...Matrix Form

$$u^{r+1} = (D - L)^{-1}U u^r + (D - L)^{-1} f$$

$$u^{r+1} = R_{GS} u^r + (D - L)^{-1} f$$

$R_{GS} = (D - L)^{-1}U$: Gauss-Seidel Iteration Matrix

Basic Iterative Methods

Let u be the solution of $Au = f$.

For an approximate solution u^r , we define

$$\text{Iteration Error: } e^r = u - u^r$$

$$\text{Residual: } r^r = f - Au^r$$

$$Au - Au^r = f - Au^r$$

$$\text{ERROR EQUATION} \rightarrow \boxed{Ae^r = r^r}$$

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Basic Iterative Methods

Error Equation

Jacobi

$$\mathbf{u}^{r+1} = \mathbf{D}^{-1}(\mathbf{L} + \mathbf{U}) \mathbf{u}^r + \mathbf{D}^{-1} \mathbf{f}$$

$$\mathbf{u} = \mathbf{D}^{-1}(\mathbf{L} + \mathbf{U}) \mathbf{u} + \mathbf{D}^{-1} \mathbf{f}$$

subtracting

$$\mathbf{e}^{r+1} = \underbrace{\mathbf{D}^{-1}(\mathbf{L} + \mathbf{U})}_{\mathbf{R}_J} \mathbf{e}^r = \mathbf{R}_J \mathbf{e}^r$$

Basic Iterative Methods

Error Equation

Gauss-Seidel

Similarly,

$$e^{r+1} = \underbrace{(D - L)^{-1} U}_{R_{GS}} e^r = R_{GS} e^r$$

Basic Iterative Methods

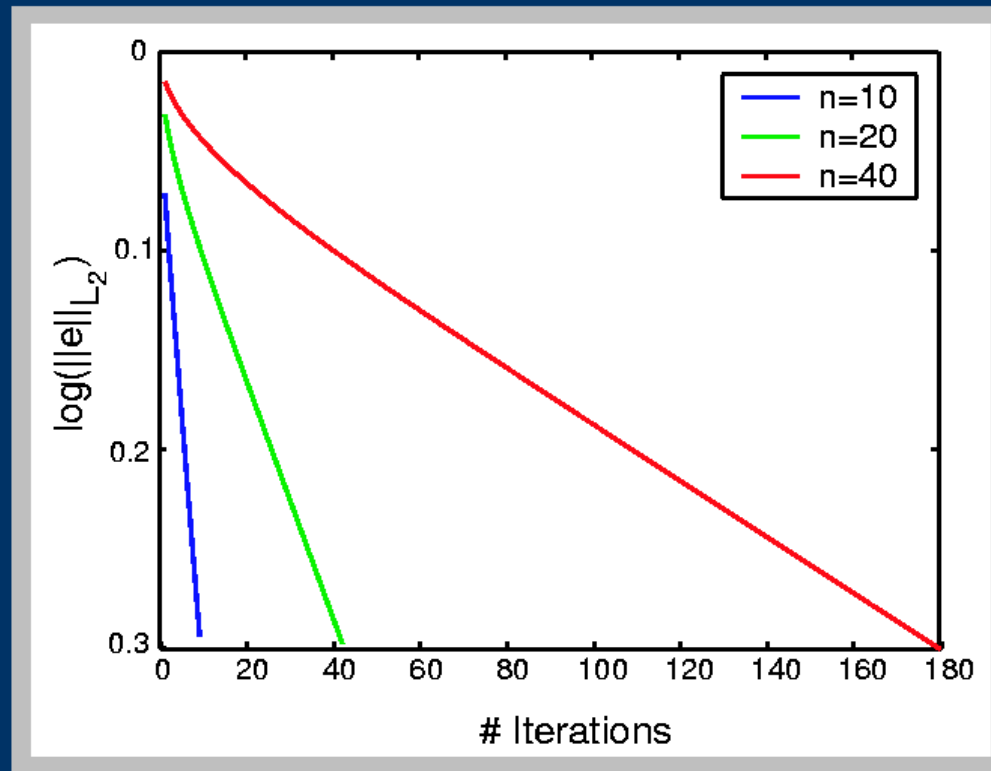
Examples

Jacobi

$$-u_{xx} = 1$$

$$u(0) = u(1) = 0;$$

$$u^0 = 0$$



Basic Iterative Methods

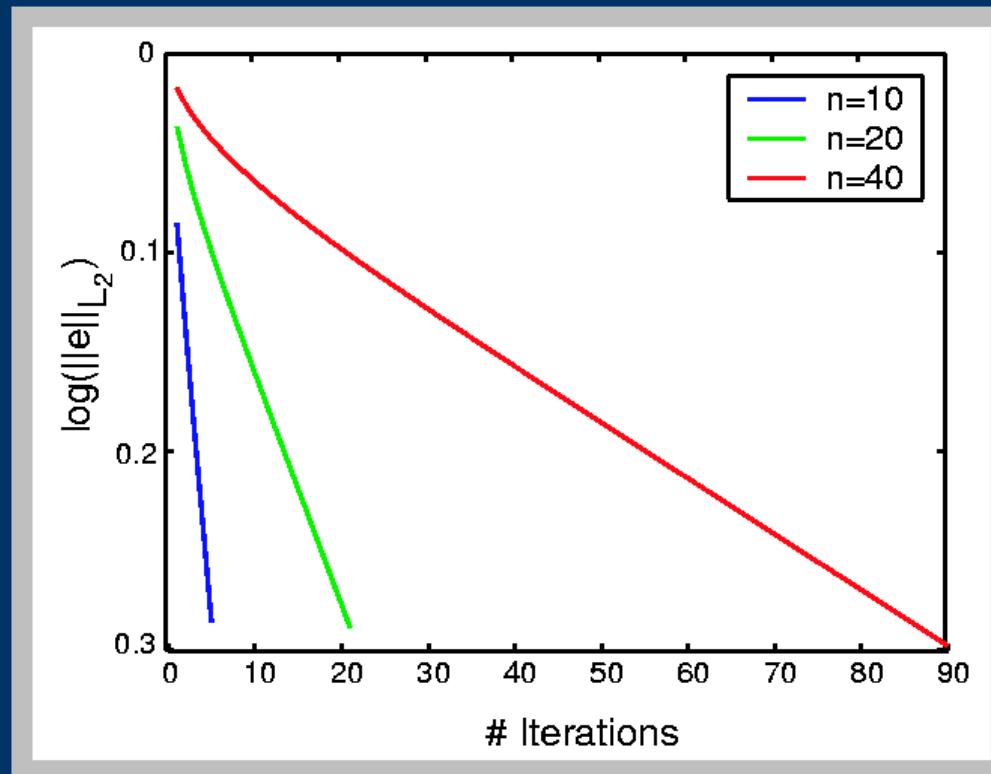
Examples

Gauss-Seidel

$$-u_{xx} = 1$$

$$u(0) = u(1) = 0;$$

$$u^0 = 0$$



Basic Iterative Methods

Examples

Observations

- The number of iterations required to obtain a certain level of convergence is $O(n^2)$.
- Gauss-Seidel is about twice as fast as Jacobi.

Why?

Convergence Analysis

$$e^r = R e^{r-1} = R R e^{r-2} = \dots = R^r e^0 .$$

The iterative method will converge if

$$\lim_{r \rightarrow \infty} R^r = 0 \iff \rho(R) = \max |\lambda(R)| < 1 . \quad \mathbf{N4}$$

$\rho(R)$ is the spectral radius.

Convergence Analysis

- If the matrix \mathbf{A} is *strictly diagonally dominant* then Jacobi and Gauss-Seidel iterations converge starting from an arbitrary initial condition.

N5

$\mathbf{A} = \{a_{i,j}\}$ is strictly diagonally dominant if

$$|a_{i,i}| > \sum_{j=1, j \neq i}^n |a_{i,j}| \text{ for all } i.$$

- If the matrix \mathbf{A} is symmetric positive definite then Gauss-Seidel iteration converges for any initial solution.

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Convergence Analysis

Jacobi

$$\mathbf{R}_J = \mathbf{D}^{-1} (\mathbf{L} + \mathbf{U}) = \mathbf{D}^{-1} (\mathbf{D} - \mathbf{A}) = \mathbf{I} - \mathbf{D}^{-1} \mathbf{A} = \mathbf{I} - \frac{h^2}{2} \mathbf{A}$$

If $\mathbf{A} \mathbf{v}^k = \lambda^k \mathbf{v}^k$,

then $\mathbf{R}_J \mathbf{v}^k = \left(\mathbf{I} - \frac{h^2}{2} \mathbf{A} \right) \mathbf{v}^k = \underbrace{\left(1 - \frac{h^2}{2} \lambda^k(\mathbf{A}) \right)}_{\lambda^k(\mathbf{R}_J)} \mathbf{v}^k$

$$\lambda^k(\mathbf{R}_J) = 1 - \frac{h^2}{2} \lambda^k(\mathbf{A})$$

Eigenvectors of $\mathbf{R}_J \equiv$ Eigenvectors of \mathbf{A}

Convergence Analysis

Jacobi

Recall ...

$$A v^k = \lambda^k v^k \quad k = 1, \dots, n$$

$$A = \frac{1}{h^2} \begin{pmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & 2 & -1 & \cdots & \vdots \\ 0 & \cdots & \cdots & \vdots & 0 \\ \vdots & \cdots & -1 & 2 & -1 \\ 0 & \cdots & 0 & -1 & 2 \end{pmatrix}$$

$n \times n$ SPD

Eigenvectors:

$$h = \frac{1}{n+1}$$

$$v_j^k = \sin(k\pi h j) = \sin\left(\frac{k\pi j}{n+1}\right)$$

Eigenvalues:

$$\lambda^k(A) = \frac{2}{h^2} [1 - \cos(k\pi h)]$$

Convergence Analysis

Jacobi

$$\lambda^k(\mathbf{R}_J) = 1 - \frac{h^2}{2} \lambda^k(\mathbf{A}) = 1 - [1 - \cos k\pi h]$$

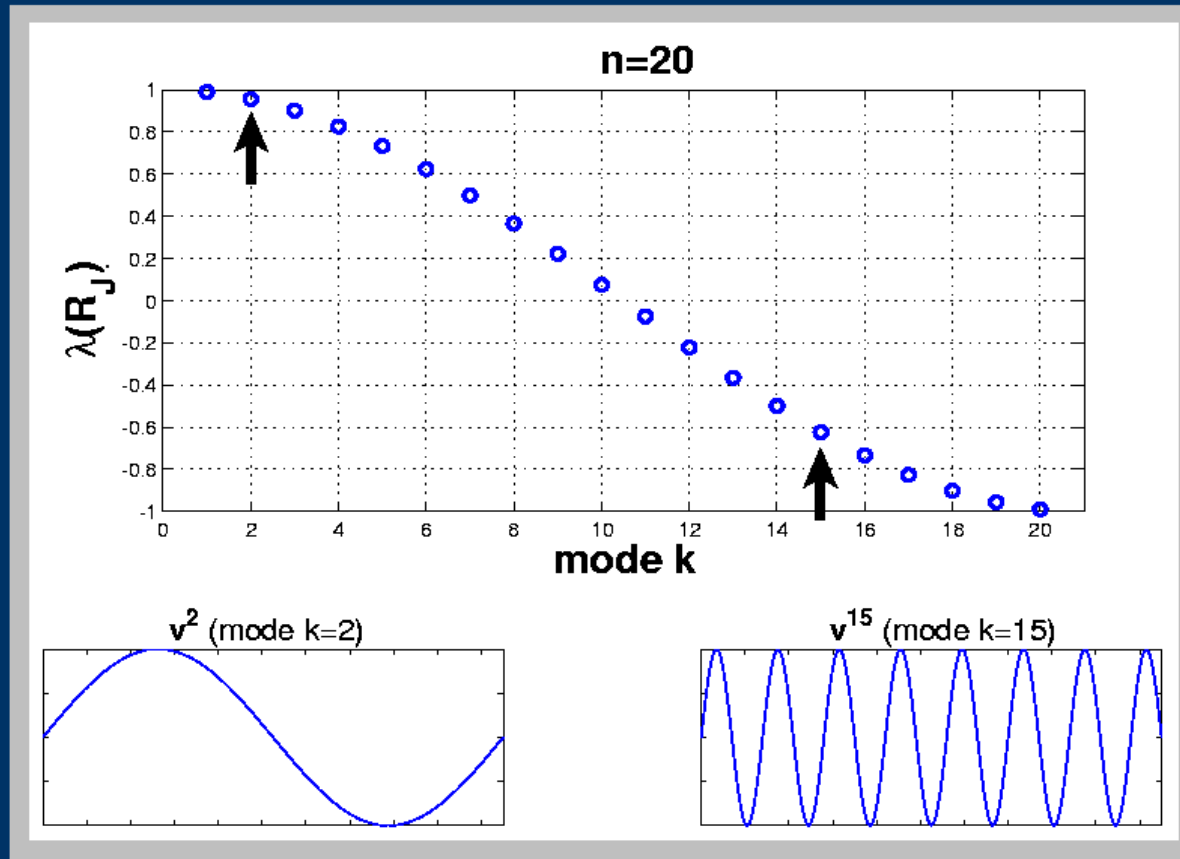
$$= \cos \frac{k\pi}{n+1} < 1, \quad k = 1, \dots, n$$

Jacobi converges for our model problem.

$$\mathbf{R}_J \mathbf{v}^k = \lambda^k(\mathbf{R}_J) \mathbf{v}^k$$

Convergence Analysis

Jacobi



Convergence Analysis

Jacobi

Write $e^0 = \sum_{k=1}^n c_k v^k$ v^k , k -th eigenvector of R_J

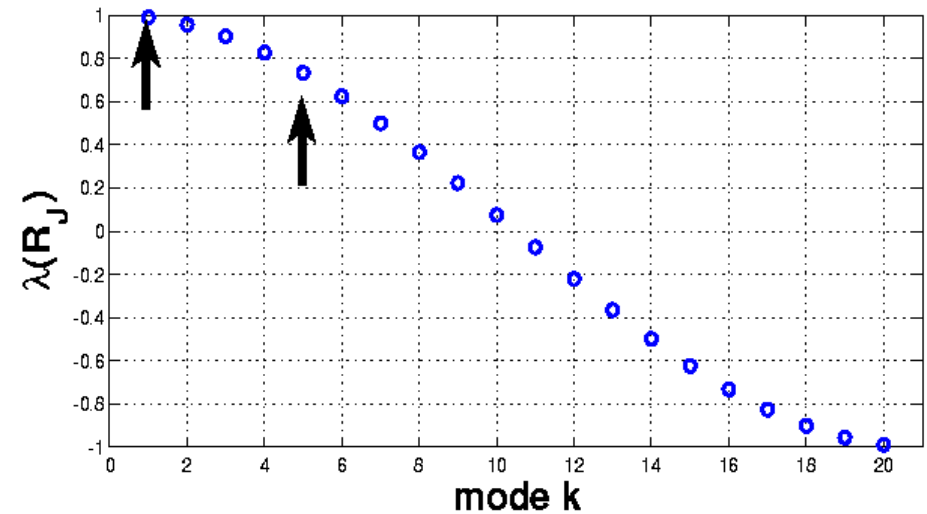
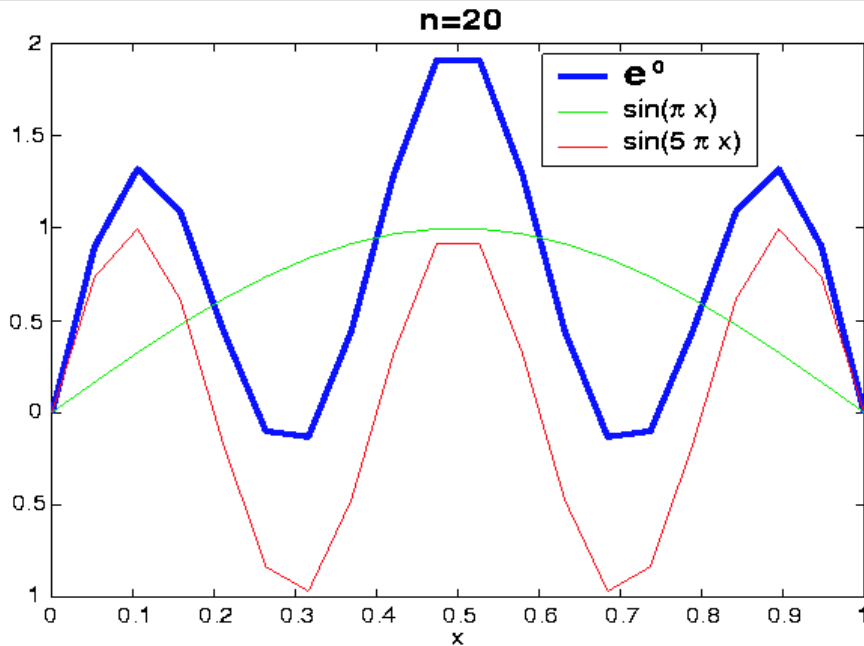
$$e^1 = R e^0 = \sum_{k=1}^n c_k \lambda^k(R_J) v^k$$

$$e^r = R^r e^0 = \sum_{k=1}^n c_k (\lambda^k(R_J))^r v^k$$

Convergence Analysis

Jacobi

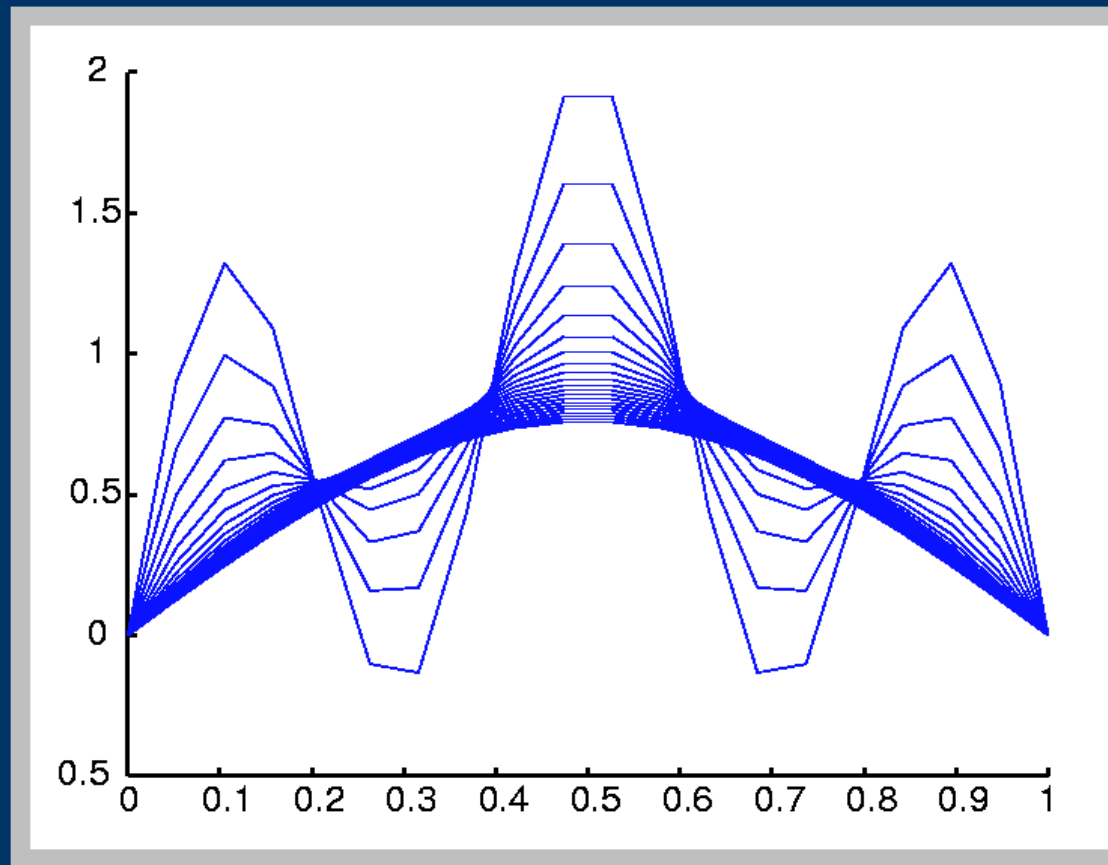
Example...



Convergence Analysis

Jacobi

...Example



Convergence Analysis

Jacobi

Convergence rate...

$$\lambda^k(R_J) = \cos(k\pi h), \quad k = 1, \dots, n$$

Largest $|\lambda^k(R_J)|$ for $k = 1, \dots, n$

Worst case $e^0 = c_1 v^1 \rightarrow e^r = c_1 \rho(R_J)^r v^1$

$$\frac{\|e^r\|}{\|e^0\|} = (\cos(\pi h))^r \simeq \left(1 - \frac{\pi^2 h^2}{2}\right)^r$$

Convergence Analysis

Jacobi

...Convergence rate

To obtain a given level of convergence; e.g., $10^{-\delta}$

$$\frac{\|e^r\|}{\|e^0\|} < 10^{-\delta}$$

$$\Rightarrow \left(1 - \frac{\pi^2 h^2}{2}\right)^r < 10^{-\delta} \rightarrow r = \frac{-\delta}{\log\left(1 - \frac{\pi^2 h^2}{2}\right)} \approx \frac{2\delta}{\pi^2 h^2} = \frac{2\delta(n+1)^2}{\pi^2}$$

\rightarrow

$$r = O(n^2)$$

Convergence Analysis

Jacobi

Convergence rate (2D)

In two dimensions, and for a uniform, $n \times n$, grid, we have

$$\lambda^{k\ell}(R_J) = 1 - \frac{h^2}{4} \lambda(A) = \frac{1}{2} [\cos(k\pi h) + \cos(\ell\pi h)]$$

$$\rho(R_J) = \cos(\pi h) = \cos\left(\frac{\pi}{h+1}\right)$$

$$h = \frac{1}{n+1}$$

Therefore,

$$r = O(n^2)$$

Convergence Analysis

Gauss-Seidel

$$R_{GS} = (D - L)^{-1} U$$

$$\lambda^k(R_{GS}) = \cos^2(k\pi h) = [\lambda^k(R_J)]^2 < 1$$

Gauss-Seidel converges for our problem

But,

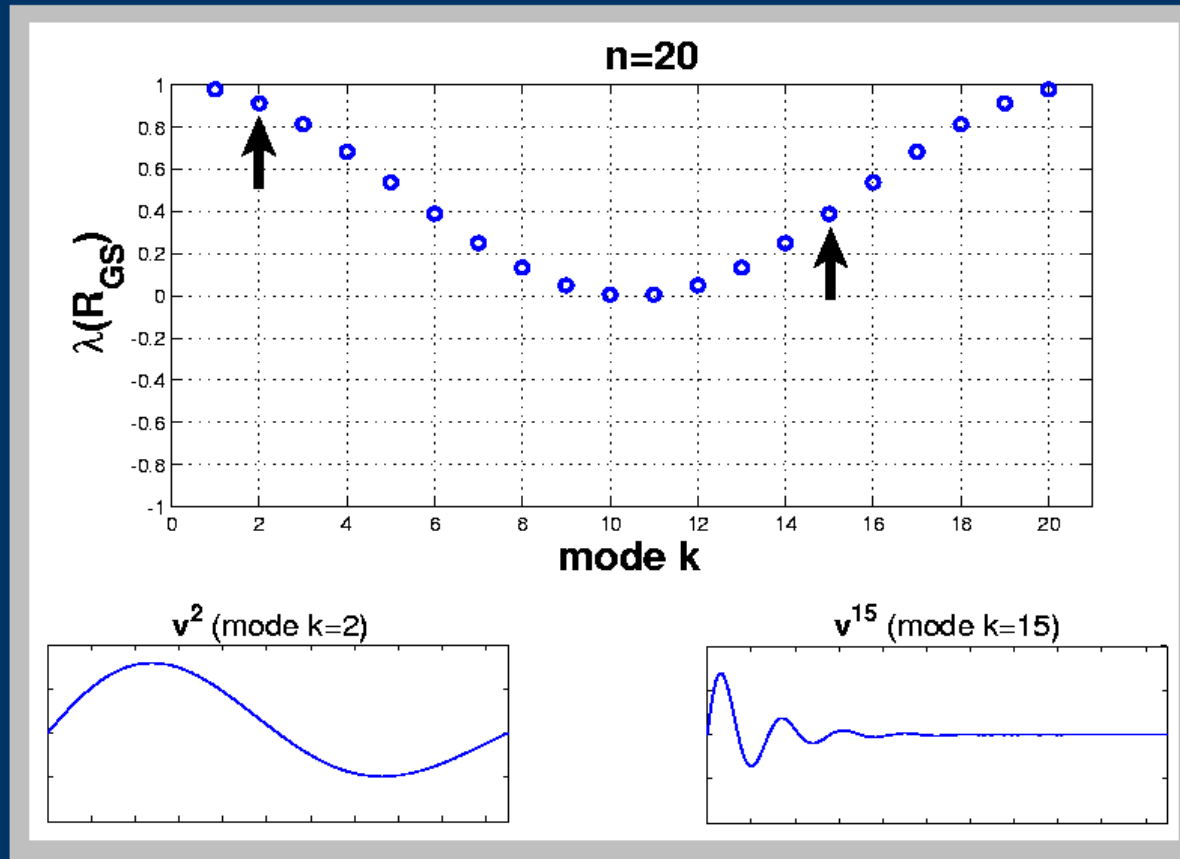
Eigenvectors of $R_{GS} \neq$ Eigenvectors of A

The eigenvectors $v^k = \{v_j^k\}_{j=1}^n$ of R_{GS} are

$$v_j^k = [\sqrt{\lambda^k(R_{GS})}]^j \sin(k\pi h j)$$

Convergence Analysis

Gauss-Seidel



Convergence Analysis

Gauss-Seidel

Convergence rate

To obtain a given level of convergence; e.g., $10^{-\delta}$

$$\frac{\|e^r\|}{\|e^0\|} < 10^{-\delta}$$

$$\Rightarrow \left(1 - \frac{\pi^2 h^2}{2}\right)^{2r} < 10^{-\delta} \rightarrow r = \frac{-\delta}{2 \log\left(1 - \frac{\pi^2 h^2}{2}\right)} \approx \frac{\delta}{\pi^2 h^2} = \frac{\delta(n+1)^2}{\pi^2}$$

→

$$r = O(n^2)$$

Comparative cost

		Iteration	Gauss Elimination
1D	$n \times n$	$O(\mathbf{n}^2 \mathbf{n}) = O(n^3)$	$O(n)$
2D	$n^2 \times n^2$	$O(\mathbf{n}^2 \mathbf{n}^2) = O(n^4)$	$O(n^4)$
3D	$n^3 \times n^3$	$O(\mathbf{n}^2 \mathbf{n}^3) = O(n^5)$	$O(n^7)$

red # iters

green cost/iter

Over/Under Relaxation

Gauss-Seidel

Main Idea

Typically

$$\mathbf{u}^{r+1} = \mathbf{R} \mathbf{u}^r + \mathbf{f}^*$$
$$\mathbf{f}^* = \mathbf{D}^{-1} \mathbf{f} \quad \text{Jacobi}$$
$$\mathbf{f}^* = (\mathbf{D} - \mathbf{L})^{-1} \mathbf{f} \quad \text{Gauss-Seidel}$$

Can we “extrapolate” the changes?

$$\begin{aligned} \mathbf{u}^{r+1} &= \omega(\mathbf{R} \mathbf{u}^r + \mathbf{f}^*) + (1 - \omega) \mathbf{u}^r \\ &= \underbrace{[\omega \mathbf{R} + (1 - \omega) \mathbf{I}]}_{\mathbf{R}_\omega} \mathbf{u}^r + \omega \mathbf{f}^* \end{aligned}$$

$\omega > 0$

Over/Under Relaxation

How large can we choose ω ?

$$\lambda^k(\mathbf{R}_\omega) = \omega \lambda^k(\mathbf{R}) + (1 - \omega)$$

Jacobi

$$\lambda^k(\mathbf{R}_J) = \cos k\pi h$$

GS

$$\lambda^k(\mathbf{R}_{GS}) = \cos^2 k\pi h$$

$\Rightarrow \rho(\mathbf{R}_\omega) < 1 \Rightarrow 0 \leq \omega_J \leq 1$ can only be
under-relaxed

$0 \leq \omega_{GS} \leq 2$ can be over-relaxed

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