6.854J / 18.415J Advanced Algorithms
Fall 2008

18.415/6.854 Advanced Algorithms

Problem Set 4

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1. In class, we have seen Klein's cycle cancelling algorithm for the Min Cost Circulation Problem (MCCP). This algorithm requires $O(mCU)$ iterations in the worst case, i.e., its running time is not polynomial in m, $\log C$ and $\log U$. In this problem, we will see how to apply the idea of *cost scaling* on this algorithm to obtain an algorithm whose running time is polynomial in m, $\log C$, and U.

   (In fact, it is possible to apply the same idea on both costs and capacities to obtain an algorithm whose running time is polynomial in m, $\log U$ and $\log C$, but this is not required in this problem.)

   Recall that in MCCP, a bidirected graph $G = (V, E)$, an anti-symmetric cost function $c : E \mapsto \mathbb{Z}$, and a capacity function $u : E \mapsto \mathbb{Z}$ are given. Let n and m denote the number of vertices and edges in G, $U = \max_{(v,w)\in E} |u(v, w)|$, and $C = \max_{(v,w)\in E} |c(v, w)|$.

   (a) For every integer i, define the cost function $c^{(i)} : E \mapsto \mathbb{Z}$ as follows:

   $$c^{(i)}(v, w) := \text{sgn}(c(v, w)) \left\lfloor \frac{|c(v, w)|}{2^i} \right\rfloor,$$

   where $\text{sgn}(x)$ is the sign of x. Notice that by the above definition, $c^{(0)}(v, w) = c(v, w)$ and $c^{(\lceil \log(C+1) \rceil)}(v, w) = 0$. Our objective is to find a way to solve MCCP for the cost function $c^{(i)}$, given its solution for $c^{(i+1)}$.

   Let f be an optimum circulation for G with the cost function $c^{(i+1)}$ and the capacity function u. Prove that if we apply Klein's cycle cancelling algorithm on G with the cost function $c^{(i)}$ and capacity function u, starting from the circulation f, then the number of iterations of this algorithm is $O(mU)$.

   (b) Use part (a) to obtain an algorithm for MCCP that requires $O(mU \log C)$ iterations.

2. Consider a directed graph $G = (V, E)$ with a length function $l : E \to \mathbb{Z}$ and a specified source vertex $s \in V$. The Bellman-Ford shortest path algorithm computes the shortest path lengths $d(v)$ between s and every vertex $v \in V$, assuming that G has no directed cycle of negative length (otherwise the problem is NP-hard). Here is a description of this algorithm:

   The Bellman-Ford algorithm computes $d(v)$ by computing $d_k(v)$ = the shortest walk[1] between s and v using exactly k edges. $d_k(v)$ can be computed by the recurrence

   $$d_k(v) = \min_{(w,v)\in E} [d_{k-1}(w) + l(w, v)].$$

[1] A walk is like a path except that vertices might be repeated.

Let $h_l(v) = \min_{k=1,\ldots,l} d_k(v)$. It can be shown that if the graph has no negative cycle then $h_{n-1}(v) = d(v)$ for all $v \in V$. Moreover, the graph has no negative cycle iff, for all v, $d_n(v) \geq h_{n-1}(v)$.

(You are not required to prove any of the above facts.)

(a) Let μ^* be the minimum average length of a directed cycle C of G, i.e.,

$$\mu^*(G) = \min_{\text{directed cycles } C} \mu(C) = \min_C \frac{\sum_{(u,v)\in C} l(u,v)}{|C|}.$$

Using the Bellman-Ford algorithm, show how to compute μ^* in $O(nm)$ time. (Hint: Use the fact that if we decrease the length of each edge by μ the average length of any cycle decreases by μ.)

(b) Can you find the cycle C with $\mu(C) = \mu^*$ using only $O(n^2)$ additional time? (In other words, suppose you are given all the values that the Bellman-Ford algorithm computes. Can you find a minimum mean cost cycle using this information in $O(n^2)$?)

3. Suppose we have n objects that we want to store in a data structure. After storing these objects in the data structure, we would like to perform m find operations on the data structure. Assume that the i'th object is accessed $k_i \geq 1$ times. Therefore, $\sum_{i=1}^n k_i = m$. We want to evaluate the performance of the data structure by computing the total running time of these m find queries (no other operation, such as delete or insert, is performed on the data structure).

(a) Show that if we store the objects in a splay tree, then no matter what the initial configuration of the splay tree is, and no matter in which order we access the objects, the total running time of the m access operations is at most

$$O\left(m + \sum_{i=1}^{n} k_i \log(\frac{m}{k_i})\right).$$

(b) Show that if we store the objects in a static binary search tree (i.e., a binary search tree that does not change by a find operation), then no matter in which order the objects are stored in the BST, and no matter in which order they are accessed, the total running time of the m access operations is at least

$$\Omega\left(m + \sum_{i=1}^{n} k_i \log(\frac{m}{k_i})\right).$$

This shows that the splay trees are within a constant factor as optimal as any static binary search tree.